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Evaluating the applicability of the finite element method for modelling of geoelectric fields

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Abstract. Geomagnetically induced currents in power systems are due to space weather events which create geomagnetic disturbances accompanied by electric fields at the surface of the Earth. The purpose of this paper is to evaluate the use of the finite element method (FEM) to calculate the magnetic and electric fields to which long transmission lines of power systems on the Earth are exposed. The well-known technique of FEM is used for the first time to simulate magnetic and electric fields applicable to power systems. Several test cases are modelled and compared with known solutions. It is shown that FEM is an effective modelling technique that can be applied to determine the electric fields which affect power systems. FEM enables an increased capability beyond the traditional methods for modelling electric and magnetic fields with layered earth conductivity structures, as spatially more complex structures can be considered using FEM. As an example results are presented for induction, due to a line current source, in adjacent regions with different layered conductivity structures. The results show the electric field away from the interface is the same as calculated for a single region; however near the interface the electric field is influenced by both regions.

Keywords. Electromagnetics (Numerical methods) – Geomagnetism and paleomagnetism (Geomagnetic induction) – Ionosphere (Electric fields and currents)

1 Introduction

During geomagnetic disturbances, the changing magnetic field produces an electric field that drives large electric currents in power transmission networks. These

geomagnetically induced currents (GIC) can cause a variety of problems for operation of power transmission systems (Boteler et al., 1998; Molinski, 2002; Pirjola et al., 2004). Traditionally this has been considered a problem for highlatitude power systems, however in recent years, GIC have been found in power systems of some mid- or low-latitude countries such as Japan (Kappenman, 2003), Brazil (Pinto et al., 2004; Trivedi et al., 2007), South Africa (Koen and Gaunt, 2003; Gaunt and Coetzee, 2007) and China (Liu et al., 2009). A notable example of GIC was the March 1989 magnetic storm that affected power systems in North America and Europe (Kappenman, 1996; Bolduc, 2002).

Modelling of GIC in power systems consists of two parts (e.g. Viljanen and Pirjola, 1994). The first step is to obtain the electric field at the surface of the Earth taking the Earth's conductivity structure into account (e.g. Hakkinen and Pirjola, 1986). The second step is calculation of GIC based on the power system's physical layout and resistances and the electric field such as discussed for the benchmark case (Horton et al., 2012). One of the largest problems is how to estimate the electric field to which a power transmission network will be exposed. This is straightforward for source fields that can be modelled as a "plane wave" and assuming a laterally uniform earth that can be represented by a layered-earth conductivity model. However, calculating the electric fields for more realistic situations involving lateral variations in both the source fields and the earth conductivity is considerably more difficult.

Modelling of the electric fields produced by line current sources over a laterally uniform earth has been performed by many authors (e.g. Hermance and Peltier, 1970; Peltier and Hermance, 1971). Viljanen et al. (2004) considered

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even more complicated ionospheric currents. Boteler and Pirjola (1998) implemented a complex image method (CIM) (Thomson and Weaver, 1975) to approximately evaluate this field for layered earth models of conductivity in an efficient manner. The Fast Hankel Transform (FHT) method can be used to calculate the integrals that give exact expressions for the electric and magnetic fields at the surface of an uniform or layered earth due to an overhead line current (Johansen and Sorensen, 1979; Pirjola, 1985). This method was used by Zheng et al. (2013) to look at the effects of magnetospheric and ionospheric currents on the surface impedance.

To model lateral variations in the earth conductivity structure requires techniques that can handle 2-D or 3-D structures. The finite element method (FEM) has been used in the past to study induction and resistivity problems (Coggon, 1971; Reddy and Rankin, 1975; Reddy et al., 1977; Pridmore et al., 1981). The main focus of these papers was to evaluate what type of conductivity structures of the Earth could be modelled. If the conductivity structure is assumed to be known, the electric and magnetic fields in the Earth can also be determined by this method.

In this paper, the FEM technique is used to study induction due to a line current source with different earth conductivity structures. First, the technique is evaluated to show that it is applicable to calculate the electric and magnetic fields in connection with GIC studies. Cases of a line current in free space, or with uniform and layered earth conductivity structures are compared with results from analytical or FHT solutions to verify the results. Finally, cases of laterally non-uniform layered earth models are considered to show the new results associated with the surface impedance that can be obtained with the FEM technique. These cases also show how the source and the earth structure influence the surface impedance calculations related to the electric fields that drive GIC in power systems.

2 The finite element method

The finite element method (FEM) originated from structural engineering in the 1960s and is now used in studies of a variety of engineering problems, e.g. structural, heat transfer, computational fluid dynamics and electromagnetism. FEM is a numerical method for solving complex differential equations subject to boundary conditions. In electromagnetic applications, the method is suited to model arbitrary distributions of conductivity in three-dimensional problems by using the Galerkin method of weighted residuals (Finlayson, 1972). In this method, a linear combination of approximation functions and coefficients is used to decompose the electromagnetic fields or potentials over finite elements (Zienkiewicz, 1971).

The advantage of introducing potentials is that the total number of the degrees of freedom can be reduced. The electric and magnetic fields can be expressed in terms of the scalar potential and the vector potential. The divergence of the vector potential is chosen to be zero. In all cases where the direction of the gradient of the conductivity is perpendicular to the electric field, the divergence of the electric field is zero resulting in no charge accumulation.

A Cartesian coordinate system is used, following the geomagnetic convention, where x is northward, y is eastward, and z is vertically down. All structures are assumed to be uniform in the y direction and to extend to infinity in the y direction. The source current is in the positive y direction resulting in the vector potential only having a y component and the gradient of the scalar potential is zero due to the uniform structure along the y direction. The governing equation in the examples in this paper is Poisson's equation for the magnetic vector potential (Eq. 1), when the current is considered only in one direction (y).

$$-\frac{1}{\mu}\nabla^2 A_y + j\omega\sigma A_y = J_s \tag{1}$$

 J_s is the source current density and A_y is the magnetic vector potential. ω is the angular frequency, μ and σ are the permeability and the conductivity of the region. σ equals zero in the air region and has conductivity values in the Earth. Applying Galerkin finite element method to Eq. (1), the governing equation can be written as (Zienkiewicz, 1971):

$$\sum_{n=1}^{n_{p}} \left[\sum_{e=1}^{n_{e}} \int \left(\frac{1}{\mu} \nabla M_{m} \cdot \nabla M_{n} + M_{m} M_{n} j \omega \sigma \right) d\Omega \right] A_{y_{n}}$$

$$= \sum_{e=1}^{n_{e}} \int \left(M_{m} J_{s} \right) d\Omega; \tag{2}$$

$$m = 1, 2, 3, \ldots, n_p$$
.

The M_m are the weighting functions and the M_n are the basis functions. n_p and n_e are the total number of nodal points and elements, respectively. The weighting functions and basis functions in the element e satisfy $M_m = N_i$ and $M_n = N_j$, where N_i and N_j are the shape functions and $i, j = 1, 2, 3, \ldots, n$. Here n denotes the total number of nodal points in each element and can be variable due to different types of elements. This can result in a large number of integral equations for large mesh structures which must be solved resulting in increased computational memory and time.

The global coordinate system (x, z) is transformed by isoparametric coordinate transformation to the natural coordinate system (ξ, η) . The shape functions at each nodal point of the rectangular element in the natural coordinate system are:

$$N_i(\xi, \eta) = \frac{1}{4} (1 + \xi_i \xi) (1 + \eta_i \eta);$$
 (3)

i = 1, 2, 3, 4.

Substituting Eq. (3) into Eq. (2) can simplify the integration procedure and the magnetic vector potential at each nodal point can be solved.

For this paper, the ANSYS version 5.7 software (http://www.ansys.com/) is used for the two dimensional simulations. Since the exact implementation within the FEM code to solve these problems is not known, the FEM results of test cases are compared with known solutions from analytical techniques to give confidence in FEM. The highly detailed equations within the FEM software can be found in the manual of the software (http://research.me.udel.edu/~lwang/teaching/MEx81/ansys56manual.pdf).

Initially, the source current is set to be a line current at a height of 100 km as done by Hermance and Peltier (1970) with the magnitude 10^6 A, and is represented as a current density with the magnitude 1 A m^{-2} in a $1 \text{ km} \times 1 \text{ km}$ square cross-sectional area. The layout of the physical model and computational model are shown in Fig. 1. The thin layer of 1 km thickness with its center at a height of 100 km is the source region where either a line current or wide current can be placed. The scale of the physical model is chosen as large as possible to ensure the magnetic fields in the x and z directions attenuate to zero at the boundaries. Thus, the depth of the physical model should be chosen to extend sufficiently far below the Earth's surface. The dashed lines in Fig. 1 indicate that the physical layers will be divided into several layers of elements for computation.

In the computational model, the element density is chosen to be sufficiently high in regions where accurate values are to be evaluated. Lower element densities can be used for regions far displaced from the region of interest. The electric and magnetic fields at the Earth surface and under the surface are most important in these computations, so a computational horizontal scale between $-2000\,\mathrm{km}$ and $2000\,\mathrm{km}$ with a resolution of 1 km is chosen. The top three conductivity layers of the Earth have a resolution of 1 km, whereas the lower two layers have 20 km and 2000 km resolutions. In the air region, the layers above and below the current are divided into ten layers.

The rectangular computational grid is used in the simulations for a free space case and for cases involving uniform and layered earth conductivity structures. The FEM values are computed at the centre of each rectangular cell by averaging the values at the nodes. The horizontal resolution of 1 km was chosen such that the values are in agreement with the analytical results for the free space case as described in the following section. The model is designed so that the electric field is only in the y direction, with the magnetic field in the x and z directions. The time period can be varied with initial comparisons done at a period of 300 s.

2.1 Free space case

To test that the boundary conditions for the FEM model are correct, a simple case of a line current flowing in free space is considered. In this case, the magnetic field has a well known analytical solution given by Ampere's Law. In Fig. 2, the calculated magnetic field at the (fictitious) Earth's surface from

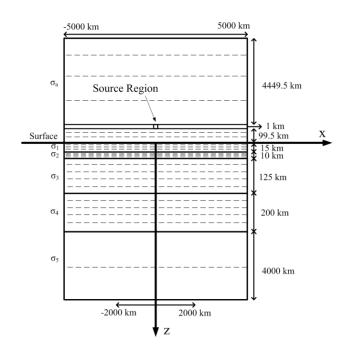


Fig. 1. Sketch of the physical and computational model used for evaluation of electric and magnetic fields. The dashed horizontal lines represent computational boundaries whereas the solid lines are physical boundaries. A large physical model is necessary to satisfy the boundary conditions of the magnetic field being sufficiently attenuated. The conductivities and thicknesses of the different layers can be varied depending on the layered Earth model. A current is placed at 100 km above the surface in a thin 1 km layer. The computational gridding of 1 km in the x dimension is omitted for clarity. For the Quebec layered earth model, $\sigma_1 = 0.00005 \, \mathrm{S} \, \mathrm{m}^{-1}$, $\sigma_2 = 0.005 \, \mathrm{S} \, \mathrm{m}^{-1}$, $\sigma_3 = 00.001 \, \mathrm{S} \, \mathrm{m}^{-1}$, $\sigma_4 = 0.01 \, \mathrm{S} \, \mathrm{m}^{-1}$ and $\sigma_5 = 0.333 \, \mathrm{S} \, \mathrm{m}^{-1}$, and the layer thicknesses are shown in the figure.

a simple line current in free space is compared with the field from FEM. The FEM results are represented by solid lines and exact values are represented by symbols. The line current is placed 100 km above the horizontal distance of 0 km. The upper panels are for the x component of the magnetic field and the lower panels are for the z component. In the right panels the differences between FEM and exact values are shown. In the free space case the magnetic field has only real components (when displacement currents are neglected) and both models agree with a maximum error of 10 nT at the 2000 nT peak of Bx just beneath the line current and 7 nT near the 1000 nT peak for Bz at a horizontal distance of \sim 100 km from directly below the line current. This amounts to a maximum relative error of ~ 0.7 % between the true solution and FEM. It is noted that the Bx component decreases to zero after about 1000 km, whereas the Bz component is still $\sim 100\,\mathrm{nT}$ at 2000 km. Due to the slow falloff of the vertical (Bz) component of the magnetic field, a larger physical model (x dimension ± 5000 km) was needed for FEM, such that the imposed boundary condition does not affect the results.

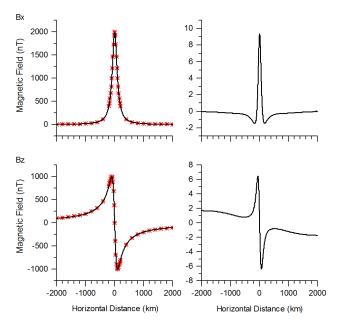


Fig. 2. The magnetic field components at z=0 and their differences from theoretical values for the free space case. The red symbols are the exact solution and the black line is the FEM solution. The graphs in the right column are the difference between the exact solution and the FEM model. The period is $300 \, \text{s}$.

The free space case highlights the system of magnetic fields that would be expected from this type of simulation. The magnetic field has both x and z components. The peak value of the x component (2000 nT) occurs directly beneath the line current whereas the z component has a value of zero below the line current. The z component has positive values for negative x and negative values for positive x, with largest magnitudes (1000 nT) at approximately ± 100 km. Now that the framework is set up, changes to the magnetic field can be noted as the conductivity structure is modified.

2.2 Uniform Earth

In this case all the layers below the surface of the Earth are set to a conductivity value of $0.001\,\mathrm{S\,m^{-1}}$ and calculations are made for a period of $300\,\mathrm{s}$. In Fig. 3, the FEM results are shown as solid lines and for comparison the results based on the Fast Hankel Transform (FHT) are shown as symbols. The FHT method gives results at the surface (z=0) for both a layered earth and uniform earth cases.

Each of the magnetic field and electric field components now has a complex value. Visually, it can be seen that the magnetic fields of FHT and FEM agree to within 1%. For the electric field, the imaginary part is more than twice that of the real part, whereas the magnetic fields components still retain much larger real parts than imaginary parts.

One clear difference is that the maximum value of the horizontal component of the magnetic field is approximately 2500 nT compared with the 2000 nT value in the free space

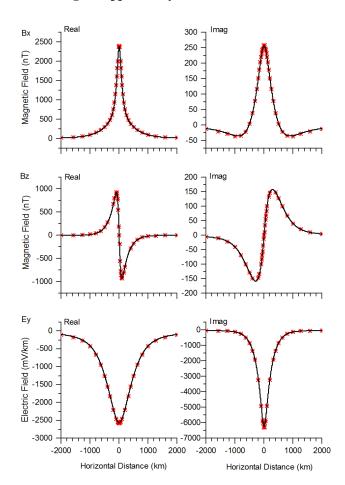


Fig. 3. The electric and magnetic field components at the surface for an uniform Earth with a conductivity of $0.001 \, \mathrm{S \, m^{-1}}$. The FEM results are the black curve whereas the FHT results are the red symbols. The period is $300 \, \mathrm{s}$.

case. The presence of the conducting Earth has increased the value of the horizontal magnetic field. This is because the magnetic field occurring on the surface of the Earth is a combination of both the direct magnetic field from the line current and the magnetic field from induced currents below the surface.

2.3 Layered Earth

As another test, calculations are made for a layered Earth conductivity structure. For this comparison the Quebec model discussed by Boteler and Pirjola (1998) and shown in Fig. 1 is used in the simulation results that are presented in Fig. 4. Once again FEM is the solid lines and FHT is the symbols. In general the results are identical to within 1 %.

By varying the time period, the frequency response of the system can be evaluated. For long periods (i.e. 1800 s or 30 min), the system is responding more like the free space case, with the electric field being substantially suppressed

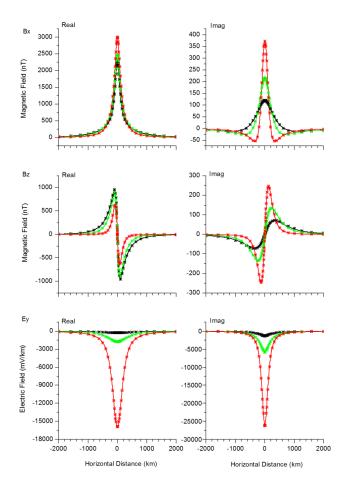


Fig. 4. The electric and magnetic field components at the Earth's surface are shown for the layered earth conductivity model of Quebec. The FEM results are the solid curves whereas the FHT results are symbols. The colours of the curves represent the periods with red being 30 s, green being 300 s and black being 1800 s.

and the magnetic field becoming almost purely real and tending to 2000 nT for Bx and 1000 nT for Bz at the maxima.

For the short period case (30 s), both the real and imaginary parts of Bx increase, whereas the real part of Bz is reduced while the imaginary part increases. For the electric field, both the real and the imaginary parts are substantially increased compared with the longer period cases.

3 Discussion

Much of the modelling efforts associated with GIC research have been designed to be able to compute the surface impedance that can be used with recorded magnetic field variations to calculate the electric fields experienced by a power system. The surface impedance is defined as: $Z = \mu_0 E/B$, where E and B are orthogonal components of the horizontal electric and magnetic fields at the surface of the Earth. In Fig. 5, the magnitude of the surface impedance

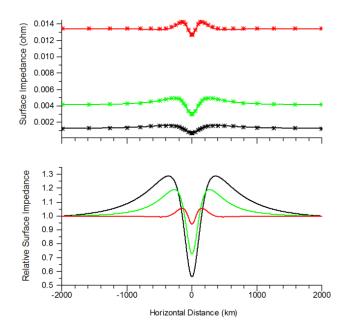


Fig. 5. The magnitude of surface impedance for the layered earth conductivity model of Quebec is shown for three different periods (red 30 s, green 300 s, and black 1800 s). The FEM results are the solid curves whereas the FHT results are symbols. The lower graph shows the relative impedance based on FEM where each value is normalized by the value at $x = -2000 \, \mathrm{km}$.

computed for the Quebec layered earth case is shown. The FEM (solid line) and FHT (symbols) results agree very well to within 0.5%. For large values of x, the surface impedance tends to the plane wave value as pointed out by Zheng et al. (2013). The surface impedance increases as the period decreases, which results in the higher frequency components of the electric spectrum being enhanced relative to the magnetic spectrum.

Beneath the line current source, the surface impedance changes due to the fields from the line current not being sufficiently planar (e.g. Viljanen et al., 1993, 1999). To further illustrate this point, in the lower part of Fig. 5, the surface impedance for each frequency is normalized by dividing by the plane wave impedance. This shows that the relative surface impedance can vary substantially from 0.55 to 1.30 in the region between $-2000\,\mathrm{km}$ and $2000\,\mathrm{km}$ for the 1800 s period. At a period of $300\,\mathrm{s}$ the range of variation is reduced to 0.72 to 1.20. At the shortest period (30 s), the range of variation is much less (0.9 to 1.1) and is much more localized between $-400\,\mathrm{km}$ and $400\,\mathrm{km}$.

Now with the FEM framework established, further problems can be studied. Consider the problem of a wide current of 200 km width centred 100 km above the earth over x=0. To simplify the comparison, the total current is still set to 1 MA. In Fig. 6 the magnitude of the surface impedances for a wide current (symbols) are compared with those for a line current (solid lines) for the periods of 30 (red), 300

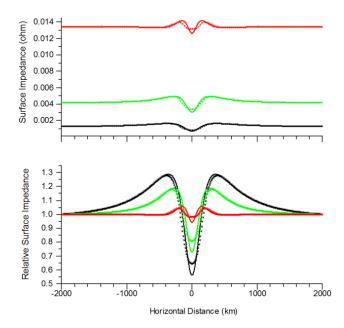


Fig. 6. The magnitude of the surface impedance for a layered earth conductivity model of Quebec is shown for three different periods for a 1 km line current (solid) and a 200 km wide current (symbols). The colours of the curves represent the periods (black 1800 s, green $300 \, \text{s}$ and red $30 \, \text{s}$). The lower graph shows the relative impedance where each value is normalized by the value at $x = -2000 \, \text{km}$. The computations are based on FEM.

(green) and 1800 (black) seconds. A wide current generates fields that are similar, but the impedance variations are broadened and not as extreme. For the long period case (black lines and symbols), the relative impedance depression is lessened directly below the wide current between $+100\,\mathrm{km}$ and $-100\,\mathrm{km}$, but it is enhanced between 100 and 400 km. The effects of the relative surface impedance at further distance are still the same as those of the simple line current.

The FEM modelling also provides the opportunity to see how the fields vary with depth within the Earth; a capability not present with FHT. Figure 7 shows results obtained with the Quebec conductivity structure, featuring vertical slices taken through the layered Earth at several different positions along the x direction for each of the components for a period of 300 s. The curves of Fig. 7 have been transformed into magnitude and phase to show clearly how the fields attenuate with increasing depth. The black lines show how the fields vary with depth directly below the line current. The blue dot-dashed line is at +100 km near the maximum of the vertical component of the magnetic field. The red line is at +800 km and illustrates how the horizontal component of the magnetic field is approaching zero. The green dot-dashed line is at +1500 km and shows how all the fields have very small values. The conductivity values of the layers are varying from a low conductivity of 0.00005 S m⁻¹ for the first, to a significantly larger value of 0.005 S m⁻¹ for the second

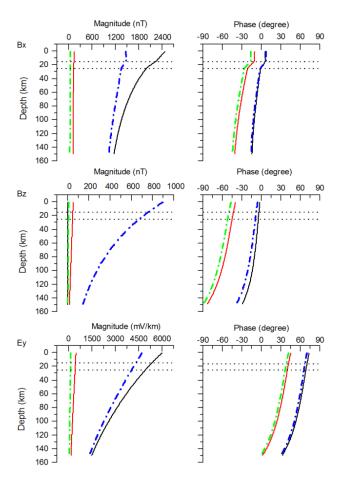


Fig. 7. The magnitude and phase variations of the electric and magnetic fields with depth at x = 0 (black), x = 100 (blue dot-dashed), x = 800 (red) and x = 1500 km (green dot-dashed) for a layered earth conductivity model of Quebec are shown for a 1 km line current located at x = 0, 100 km above the surface and having a period of 300 s. The computations are based on FEM.

and a conductivity $0.001 \, \mathrm{S \, m^{-1}}$ for the third layer. The layer transitions (marked by dashed lines in the upper two panels) are clearly observed in both the magnitude and the phase of the x component of the magnetic field especially near the source region (black and blue dot-dashed curves). Clearly, the ability to examine the changes of the fields with depth is enhanced by using FEM.

The FEM technique can also be used to model complex conductivity structures of the Earth as shown in Fig. 8 where there is an interface region between two layered earth structures. In this model the layered earth structure of Quebec is used for x < 0 and the layered earth structure of British Columbia (BC) is used for x > 0. Figure 9 shows the results of the FEM simulation for a line current source placed 100 km above the interface region at x = 0. The black curve is for the combined case with the two different layered earth structures (see Fig. 8). For comparison, the red curve is for the case of the Quebec layered earth structure, assuming that the

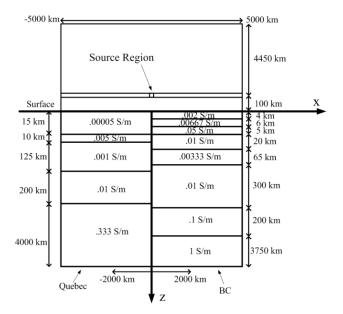


Fig. 8. The combined earth model is used for the evaluation of electric and magnetic fields. For x < 0 the Quebec layered earth model is used. For x > 0 the British Columbia layered earth model is used. The conductivities and thicknesses of the different layers are shown. A current is placed at $100 \, \text{km}$ above the surface in a thin 1 km layer.

conductivity profile is the same for both positive and negative x. Using this same assumption, the green curve represents the results for the BC layered earth structure. Clearly it is shown that at large distances from the interface, the fields with the combined model tend to the same values as the fields for the Quebec or BC model on their respective sides of the interface. The Quebec structure represents a highly resistive structure whereas the BC structure represents a more conductive structure. The most significant feature is that the fields are no longer symmetric with respect to the location of the line current source. The electric field maximizes on the Quebec side whereas the magnetic field maximizes on the BC side. In the interface region the combined model does not seem to be just the linear superposition or average of the two models. For the BC side, the fields become similar after 100 km from the interface but for the Quebec side, the fields do not become similar until at least 500 km.

To check how the fields are affected by the location of the source, model calculations are made of the fields produced by line currents on either side of the interface. Figure 10 shows the results for the simulation when the line current is moved 300 km to the Quebec side from the interface. The combined results agree with Quebec model results further than 100 km from the interface, and with the BC model results further than 300 km from the interface. Clearly near the interface region, the fields with the combined model are not the same as the fields produced by either individual model. Figure 11 shows simulation results for the line current located 300km to the BC side from the interface. It is seen that

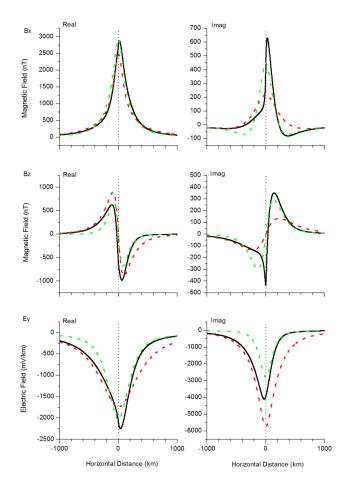


Fig. 9. The electric and magnetic field components at the Earth's surface are shown for three different cases. The red curves represent the results with the Quebec layered earth model, the green curves represent the results with the BC layered earth model and the black curves represent the results with the combination of the layered earth structure of Quebec for x < 0 and the layered earth structure of BC for x > 0 (see Fig. 8). The line current is located $100 \, \text{km}$ above the x = 0 point, which is the interface between the Quebec structure and the BC structure. The computations are based on FEM with a period of $300 \, \text{s}$.

the combined results are the same as with the BC model for distances greater than 100 km from the interface. The fields with the combined model are different from those with the Quebec model until at least 500 km from the interface. Once again the fields near the interface region are not the same as the fields produced by either individual model.

The surface impedances for the three combined cases are presented in Fig. 12. On the BC side the surface impedance agrees well for all three cases, whereas on the Quebec side there are substantial deviations from what was presented in Fig. 5 for a complete Quebec model. The location of the line current relative to the interface clearly affects the surface impedance, especially on the Quebec side of the model.

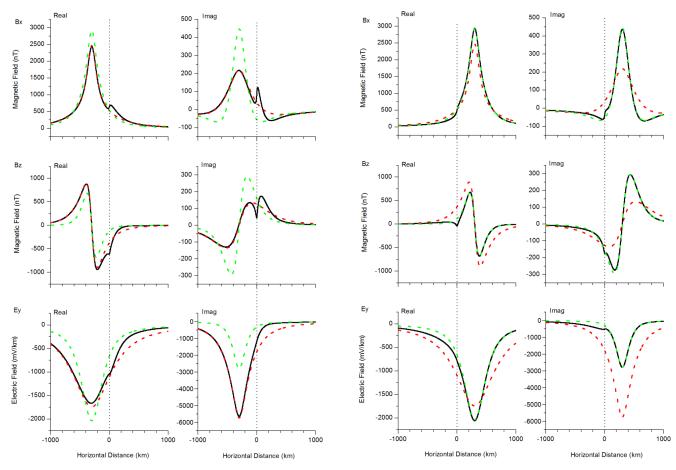


Fig. 10. Same as Fig. 9 but the line current is displaced from the interface region to x = -300 km.

Fig. 11. Same as Fig. 9 but the line current is displaced from the interface region to $x = 300 \, \text{km}$.

4 Conclusions

In this paper, the well-known technique of FEM was used for the first time to calculate magnetic fields and associated electric fields that could drive GIC in power systems. It has been demonstrated that the results from FEM and the results of analytical expressions or FHT calculations are identical to within 1%, when a sufficiently large model was chosen for FEM with a sufficiently good resolution of elements. FEM can be considered for problems that have no simple physical layout or where the mathematical equations are too difficult to solve in practice. In addition FEM gives the values below the surface of the Earth and not just at the Earth's surface. The advantage of the FEM toolkit is that once the physical and computational models are established then parameters can be adjusted to give solutions for similar problems. FEM is capable of calculating the fields below the surface of the earth without the need to derive complex mathematical expressions. FEM can be further used for complicated current systems and/or spatially varying conductivity models.

One of the limitations of FEM is that the amount of computational power increases with the complexity of the layered

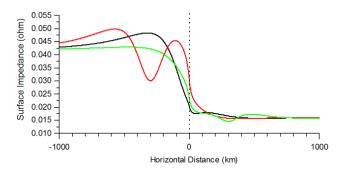


Fig. 12. The surface impedances for the combined models of the three different cases of Figs. 9–11. The black curve is the surface impedance when the line current is located above the interface region. The red curve is the surface impedance when the line current is located at $-300 \, \text{km}$ and the green curve is the surface impedance when the line current is located at $300 \, \text{km}$. The computations are based on FEM with a period of $300 \, \text{s}$.

earth structures. In three-dimensional FEM, the simulations still have to be run on a supercomputer. For simple cases such as free space case, it is computationally more efficient to use analytical solutions or other codes such as FHT. As the complexity of the problem increases, the advantage of FEM is demonstrated.

The FEM technique was used to estimate the surface impedance of both line currents and wide currents. The FEM values for the electric field and the magnetic field can be used directly to calculate the surface impedance. Also, FEM properly handles situations of regions close to the source so the assumption of a plane wave source is not necessary.

FEM was used to evaluate a more complex model comprised of two different layered models and shows the complexity of the surface impedance in the interface region between the two structures. The variations of the fields in the interface region are of prime interest to GIC researchers. This paper shows the value of using FEM in GIC studies and important new results for the surface impedance, commonly used in GIC modelling.

Using FEM, a wide variety of physical systems with different input sources can be simulated in a very short period of time. Computational time for each of the simulations is less than 10 min on a typical laptop computer. In future work, FEM will be used to investigate the effects of boundaries between layered conductivity blocks of the Earth, in particular the "coast effect" at the ocean-land interface emphasising applications to GIC research.

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